An Interpretable Distance Measure for Multivariate Non-Stationary Physiological Signals

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[Context and motivation](#page-1-0)

[The d_symb symbolization and distance measure](#page-4-0) [Experimental results](#page-8-0) [Comparing multivariate non-stationary physiological signals](#page-2-0) [Our approach: symbolization, then distance on strings](#page-3-0)

I) [Context and motivation](#page-1-0)

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[The d_symb symbolization and distance measure](#page-4-0) [Experimental results](#page-8-0) [Comparing multivariate non-stationary physiological signals](#page-2-0) [Our approach: symbolization, then distance on strings](#page-3-0)

I.1) Comparing multivariate non-stationary physiological signals

Motivation: study of human locomotion [\[3\]](#page-13-0)

- Angular velocity recorded on the left and right feet using a pair of sensors.
- Protocol: standing, walking, turning around, walking back, and standing.
- Multivariate signals with $d = 16$ dimensions: norms of the STFT (Short Time Fourier Transform) of each foot recording (univariate signal).

[Context and motivation](#page-1-0)

[The d_symb symbolization and distance measure](#page-4-0) [Experimental results](#page-8-0) [Comparing multivariate non-stationary physiological signals](#page-2-0) [Our approach: symbolization, then distance on strings](#page-3-0)

I.2) Our approach: symbolization, then distance on strings

- **•** Popular distances between multivariate time series (Euclidean distance, Dynamic Time Warping) can not handle non-stationarity.
- Our distance is interpretable and can compare non-stationary signals: (i) symbolization, (ii) distance on strings.

Symbolization technique

- ¹ Segmentation step: a real-valued signal of length *n* is split into *w* segments (*w* < *n*).
- 2 Quantization step: each segment is mapped to a discrete value taken from a set of *A* symbols. Example of set of symbols with $A = 5$: $\{a, b, c, d, e\}$.

II) [The d_symb symbolization and distance](#page-4-0) [measure](#page-4-0)

[Distance measure](#page-7-0)

II) The d_symb symbolization and distance measure

Steps of *dsymb*

- **1** Segmentation: change-point detection (on the mean).
- ² Quantization: *K*-means clustering (of the means per segment), with $K = A$.
- ³ Distance: general edit distance between the resulting symbolic signals.

[Segmentation](#page-6-0) [Distance measure](#page-7-0)

II.1) Segmentation

Change-point detection: finding the *w* [∗] unknown instants $t_1^* < t_2^* < \ldots < t_{w^* + 1}^*$ where the mean of signal $x = (x_1, \ldots, x_n)$ change abruptly:

$$
\left(\hat{w}, \hat{t}_1, \ldots, \hat{t}_{\hat{w}+1}\right) = \underset{\left(w, t_1, \ldots, t_{w+1}\right)}{\arg \min} \sum_{k=0}^{w+1} \sum_{t=t_k}^{t_{k+1}-1} ||x_t - \bar{x}_{t_k:t_{k+1}}||^2 + \lambda w, \quad (1)
$$

where $\bar{x}_{t_k:t_{k+1}}$ is the empirical mean of $\{x_{t_k},\ldots,x_{t_{k+1}-1}\}$ and $\lambda>0$ is a penalization parameter.

Remarks

- Compromise between the reconstruction error and the number of change-points.
- When λ is small, many change-points are detected. For calibration purposes, we use $\lambda = \ln(n)$ [\[4\]](#page-14-1).
- Solved using the Pruned Exact Linear Time (PELT) algorithm [\[1\]](#page-13-1), which is shown to have $\mathcal{O}(n)$ complexity (under some assumptions).

[Segmentation](#page-6-0) [Distance measure](#page-7-0)

II.2) Distance measure

The *dsymb* distance measure: levering the general edit distance

1 Preprocessing.

- Including the segment length information: replicating each symbol proportionally to its segment length. Example: abd becomes aabbbbdd.
- Shortening: dividing each length by the minimum length. Example: aabbbbdd becomes abbd.
- 2 Applying the general edit distance with custom costs.
	- Edit distance on strings (a.k.a Levenshtein distance [\[2\]](#page-13-2)): minimal cost of a sequence of operations that transform a string into another.
	- Allowed simple operations and their costs:
		- Substitution: Euclidean distance between the cluster centers of the symbols.
		- **Insertion: max of substitution costs.**
		- Deletion: max of substitution costs.
	- Total cost: sum of the costs of the simple operations.

[Interpretation of the d_symb symbolization](#page-9-0)

III) [Experimental results](#page-8-0)

[Interpretation of the d_symb symbolization](#page-9-0) [Interpretation of the d_symb distance measure](#page-10-0)

III.1) Interpretation of the d symb symbolization

Color bars for 60 recordings.

Observations

- The general structure is coherent with the protocol.
- Change-point detection finds stationary segments.
- **Each symbol can be** associated with a type of behavior.

III.2) Interpretation of the d_symb distance measure

Benchmark: computing the silhouette score

- We have 3 groups of patients:
	- healthy,
	- neurological pathology (such as cerebellar disorder),
	- or orthopedic pathology (such as knee injuries).
- The silhouette coefficient is calculated using the distance matrix and the ground truth labels corresponding to the patient group.

[Interpretation of the d_symb symbolization](#page-9-0) [Interpretation of the d_symb distance measure](#page-10-0)

III.2) Interpretation of the d symb distance measure

Robustness to the difference in length

Observations

- The two scaled univariate gait signals are different in length...
- **o** but are considered similar by *dsymb* (applied to their multivariate spectrograms).

Thank you for your attention.

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[Interpretation of the d_symb symbolization](#page-9-0) [Interpretation of the d_symb distance measure](#page-10-0)

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